

# On Difference Operation in Linear Prediction

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## Abstract

The relationship between the predictors obtained on differenced data and those on original data is derived for both the covariance method and the autocorrelation method. The physical interpretation of the derived relationship is discussed in connection with spectral enhancement.

## 1. Difference Operation in the Covariance Method

The linear prediction model for a sampled  $\{y_n\}$  is expressed in the form

$$y_n \doteq \sum_{i=1}^p \alpha_i y_{n-i} \quad (1)$$

where  $\alpha_i$  denotes the  $i$ th predictor and  $p$  is the prediction order. In matrix form, eq.(1) can be written as

$$\begin{matrix} y \\ m \times 1 \end{matrix} \doteq \begin{matrix} Y & \alpha \\ m \times p & p \times 1 \end{matrix} \quad \text{or} \quad \begin{matrix} [y \ \vdots \ Y] & \alpha \\ m \times (p+1) & (p+1) \times 1 \end{matrix} \doteq \begin{matrix} 0 \\ m \times 1 \end{matrix} \quad (2)$$

where

$$y = \begin{bmatrix} y_n \\ \vdots \\ y_{n-m+1} \end{bmatrix} \quad Y = \begin{bmatrix} y_{n-1} & \cdots & y_{n-p} \\ \vdots & & \vdots \\ y_{n-m} & \cdots & y_{n-m-p+1} \end{bmatrix} \quad \text{and} \quad \alpha = \begin{bmatrix} -1 \\ \alpha \\ \alpha_p \end{bmatrix} = \begin{bmatrix} -1 \\ \alpha_1 \\ \vdots \\ \alpha_p \end{bmatrix} \quad (3)$$

Vector  $a$  is called the augmented predictor vector for  $\alpha$ . The normal equation for the covariance method is obtained by premultiplying both sides of eq. (2) by  $Y^T$ .

$$Y^T y = Y^T Y \hat{\alpha} \quad (4)$$

where the product matrix  $Y^T Y$  represents the covariance matrix of  $\{y_n\}$ .

The least-squares solution for  $\hat{\alpha}$  or  $\hat{a}$  is derived from the normal equation (4) and is expressed as

$$\hat{\alpha} = Y^+ y \quad \text{or} \quad \hat{a} = \begin{bmatrix} -1 \\ \hat{\alpha} \end{bmatrix} = \begin{bmatrix} -1 \\ Y^+ y \end{bmatrix} \quad (5)$$

where  $Y^+$  denotes the generalized inverse of  $Y$  and is usually identical to  $(Y^T Y)^{-1} Y^T$  except for rank deficient cases. That was the formulation of the covariance method by the generalized inverse of matrices.

In the same way, the linear prediction model for the differenced sequence of the form  $\{y_n - w y_{n-1}\}$  is expressed as

$$y_n - w y_{n-1} \doteq \sum_{i=1}^p \beta_i (y_{n-i} - w y_{n-i-1}) \quad (6)$$

where  $\beta_i$  denotes the  $i$ th predictor for the differenced data. Equation 6 is written in matrix form as

$$\begin{matrix} [\Delta y & \vdots & \Delta Y] & b \\ m \times (p+1) & (p+1) \times 1 & m \times 1 \end{matrix} \doteq \begin{matrix} 0 \\ m \times 1 \end{matrix} \quad (7)$$

where

$$\Delta y = \begin{bmatrix} y_n - w y_{n-1} \\ \vdots \\ y_{n-m+1} - w y_{n-m} \end{bmatrix}, \quad b = \begin{bmatrix} -1 \\ \beta \\ \beta_p \end{bmatrix} = \begin{bmatrix} -1 \\ \beta_1 \\ \vdots \\ \beta_p \end{bmatrix}$$

and

$$\Delta Y = \begin{bmatrix} y_{n-1} - w y_{n-2} & \cdots & y_{n-p} - w y_{n-p-1} \\ \vdots & & \vdots \\ y_{n-m} - w y_{n-m-1} & \cdots & y_{n-m-p+1} - w y_{n-m-p} \end{bmatrix} \quad (8)$$

Here again,  $b$  is the augmented predictor vector for  $\beta$ .

In order to investigate the relationship between  $\hat{a}$  and  $\hat{b}$ , it will be reasonable to start with the same number of prediction equations on the same number of data samples. Standing on that point, we assume  $\beta_p = 0$  with the intention of preparing the same number of differenced data that can provide the same number of prediction equations as those on the original data. Under this assumption the  $p$ th column of  $\Delta Y$  is arbitrary and eq.(7) can be modified as follows:



