

Computational Semantics

Day 4: Dominance Graphs, Round Two

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ESSLLI 2004, Nancy

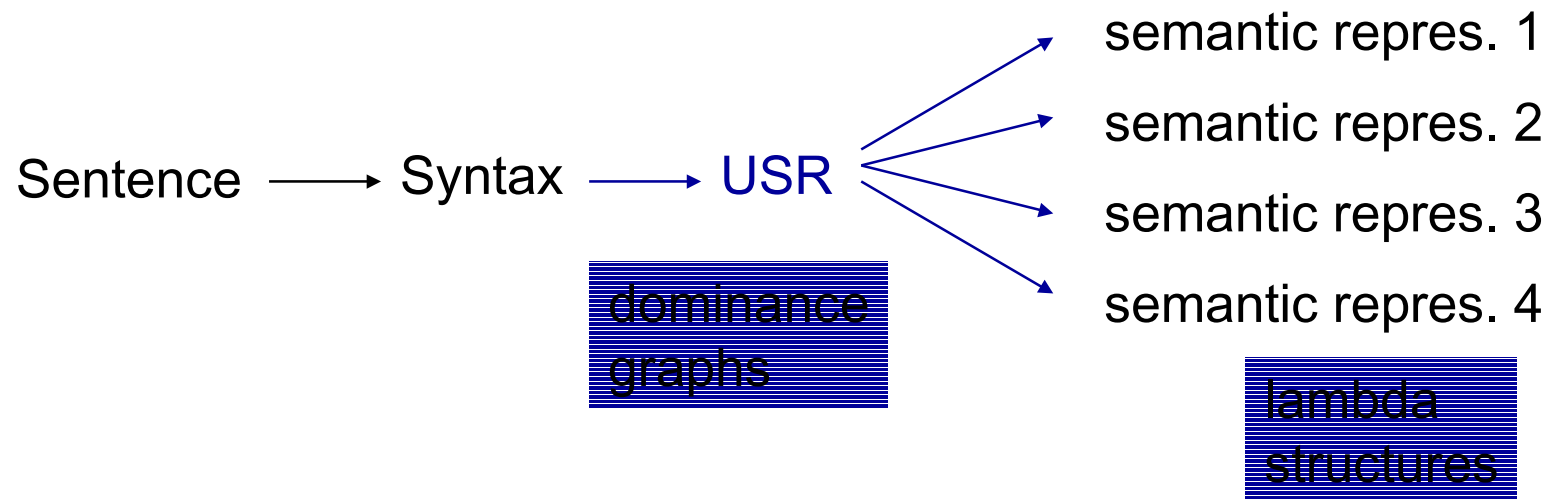


Overview

- ◆ Semantics construction for dominance graphs
- ◆ Implementation in our Prolog framework

- ◆ Solving dominance graphs
- ◆ Implementing the graph solver

Recap: Yesterday

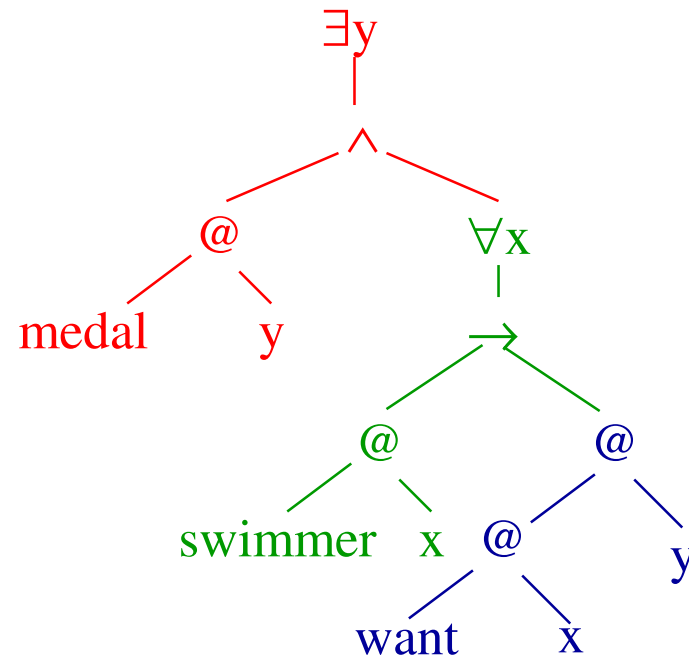
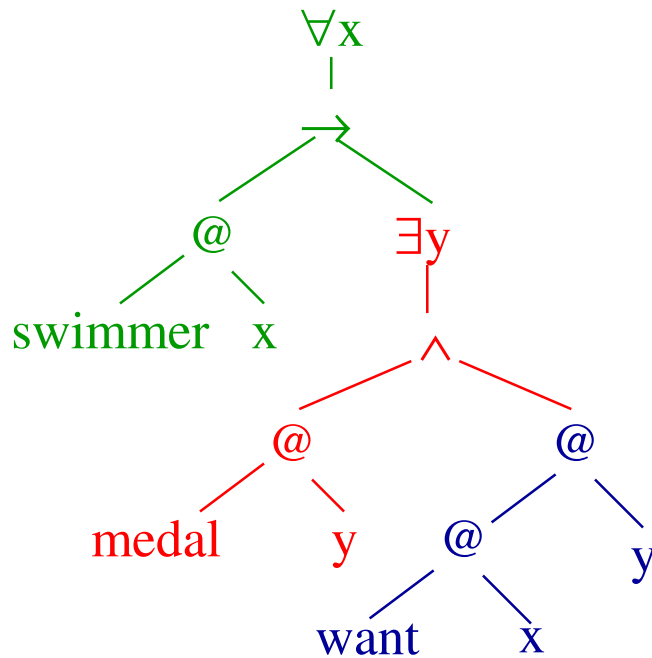


Recap: Yesterday

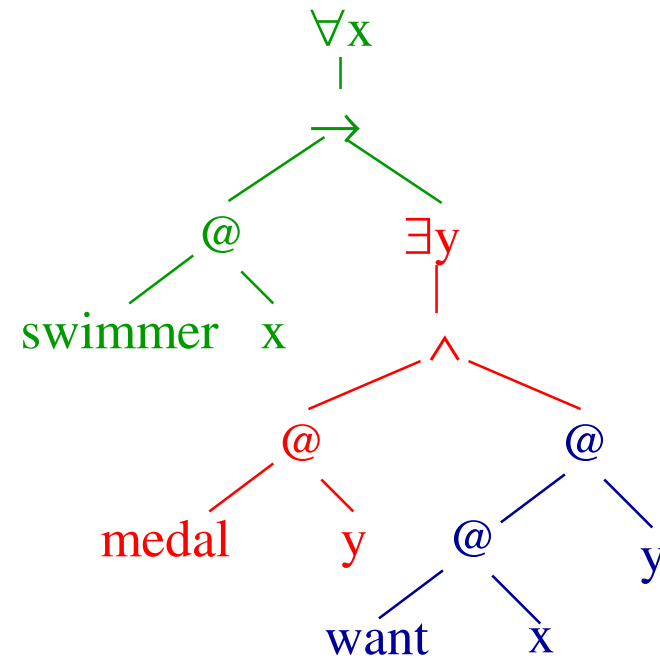
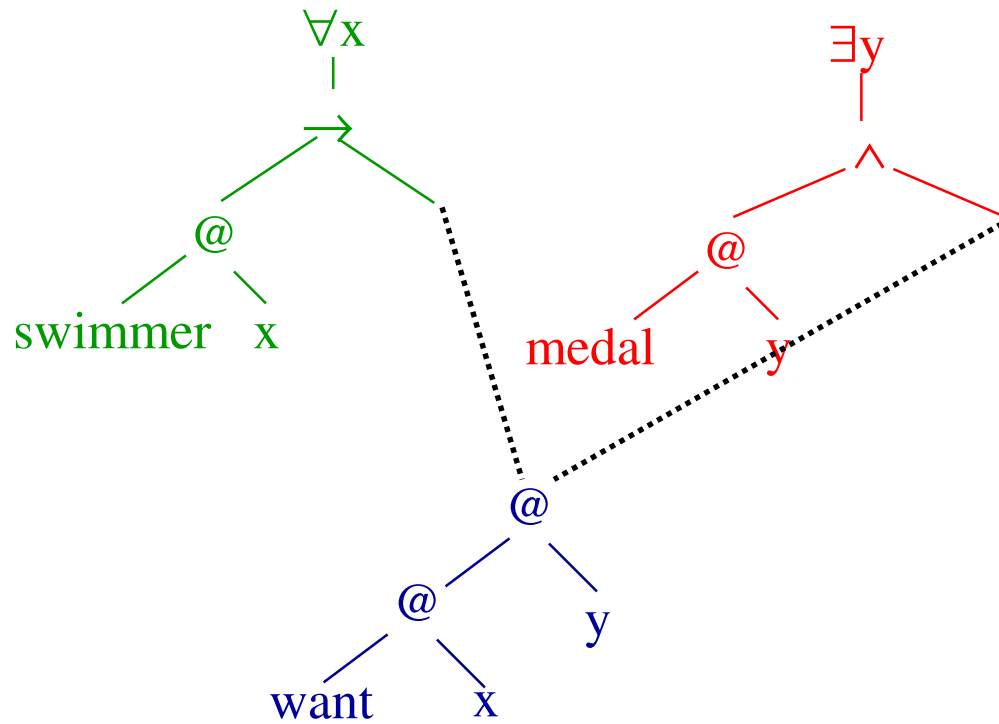
"Every swimmer wants a medal."

$\exists y \text{ medal}(y) \wedge \forall x. \text{swimmer}(x) \rightarrow \text{want}(x,y)$

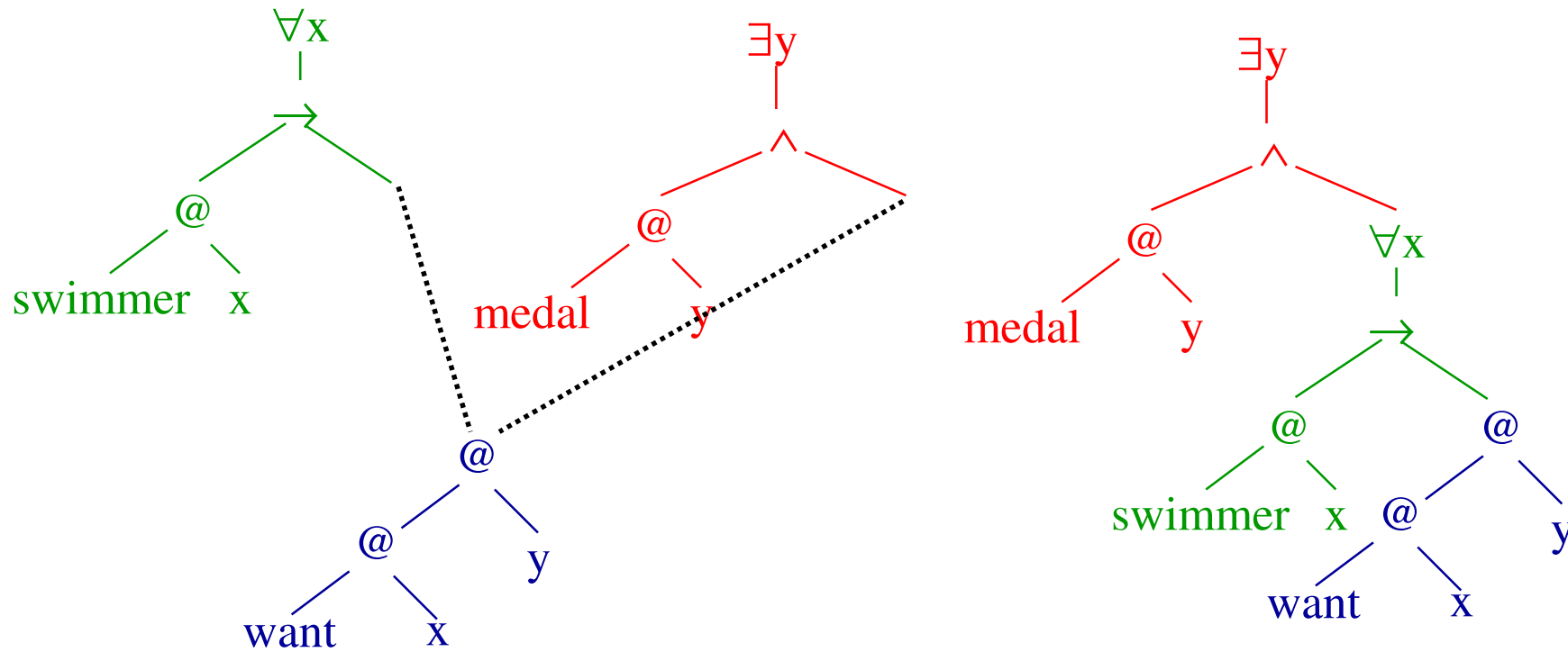
$\forall x. \text{swimmer}(x) \rightarrow \exists y \text{ medal}(y) \wedge \text{want}(x,y)$



Recap: Yesterday



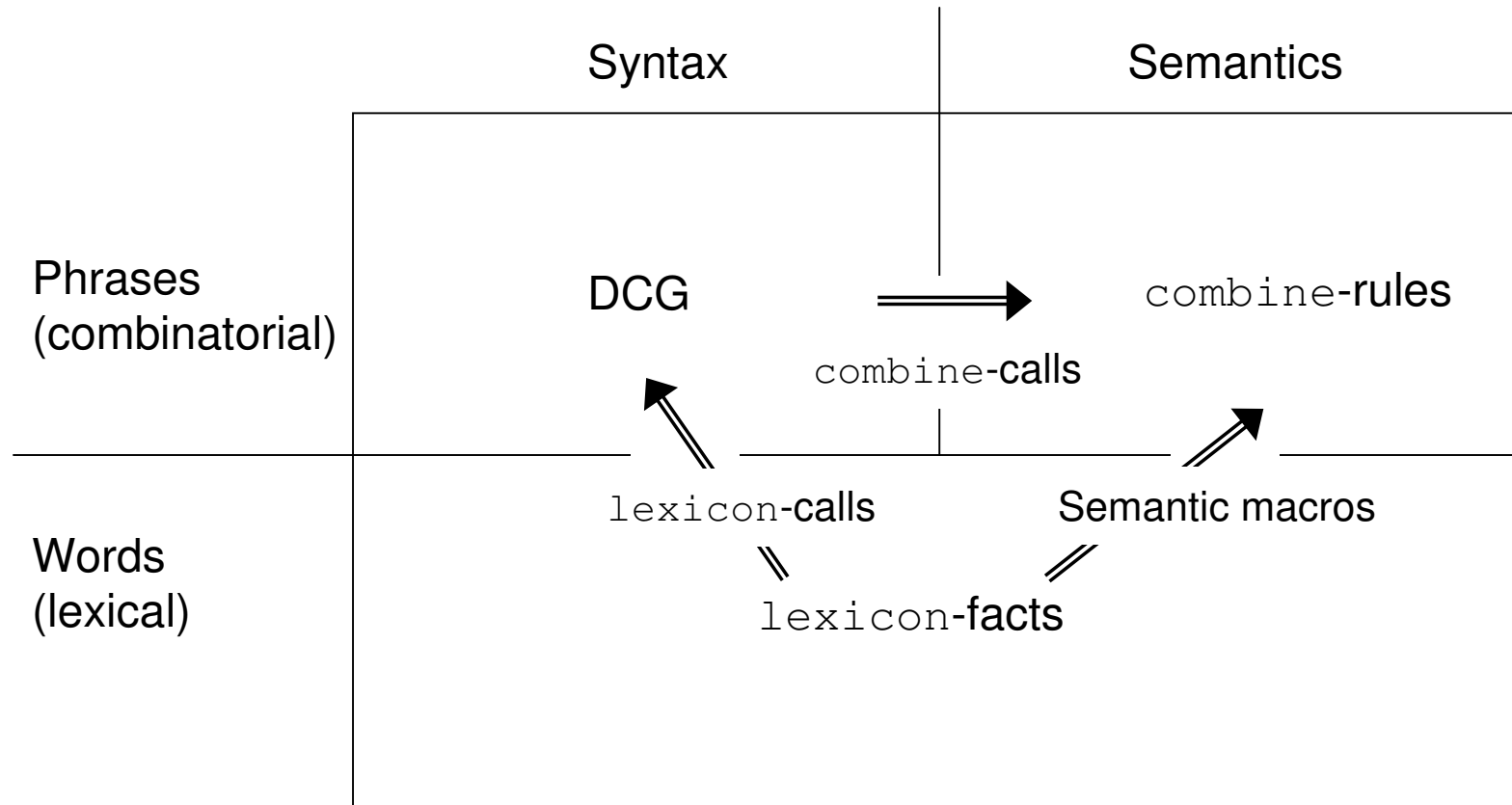
Recap: Yesterday



Semantics Construction

- ◆ First remaining question:
 - How do we construct a dominance graph from a syntactic analysis?
- ◆ We use Tuesday's modular syntax-semantics framework.
- ◆ Replace semantic macros and `combine` rules by new ones.

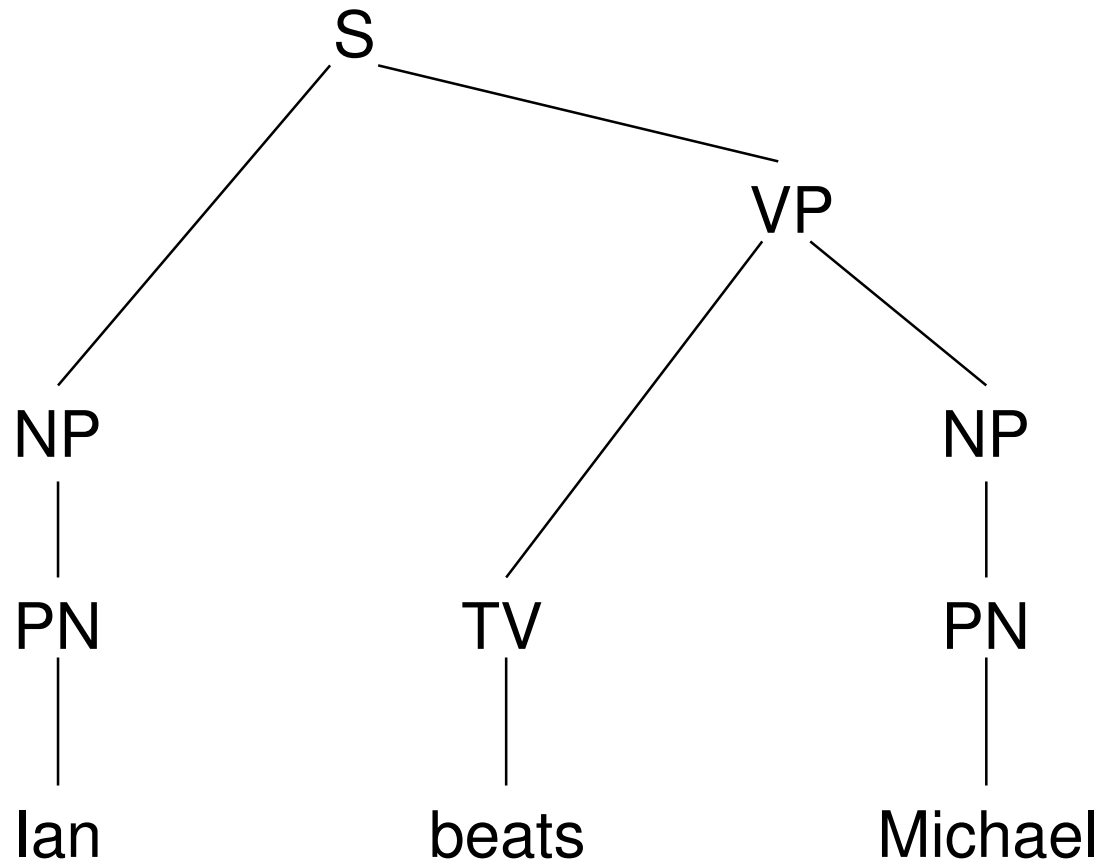
Semantics Construction Architecture



Semantics Construction: Principles

- ◆ We use exactly the same DCG grammar and lexicon facts as on Tuesday.
- ◆ For every node in the syntax tree, we derive a dominance graph that represents the semantic readings.
- ◆ Prolog representation of dominance graphs:
`usr (Nodes, LCs, DCs, BCs)`
- ◆ First element of node list is the **interface node** (or **root**). Use this to connect the subgraph to other subgraphs.

A Simple Example



Semantic macros for the example

- ◆ Most semantic macros introduce graphs that have exactly one node, which is labelled by the "core semantics".

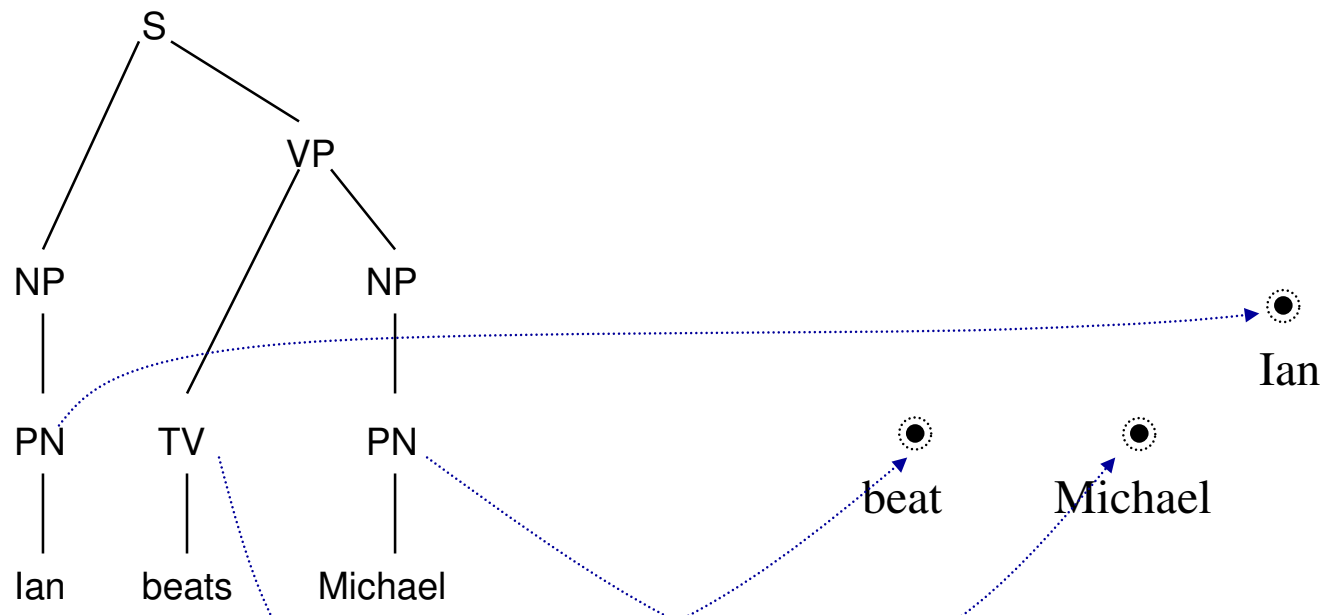
- ◆ Macro for proper names:

```
pnSem (Symbol,  
      usr ([Root], [Root:Symbol], [], [])) .
```

- ◆ Macro for transitive verbs:

```
tvSem (Symbol,  
      usr ([Root], [Root:Symbol], [], [])) .
```

Semantics construction: The simple example



- lexicon facts
- semantic macros

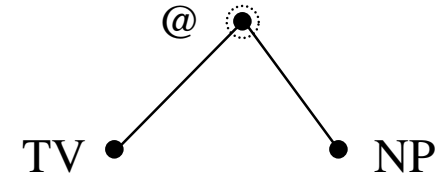
Combining verbs and NPs

- ◆ General rule: The interface node of a graph for a noun phrase is the node that will be plugged into the verb as an argument.
- ◆ For proper names, this means we don't need to do any real work:

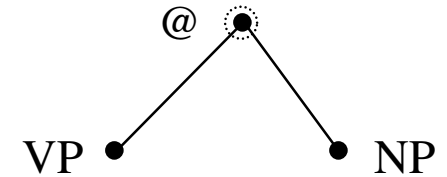
```
combine (np:NP, [pn:NP]) .
```

Combine rules for verbs

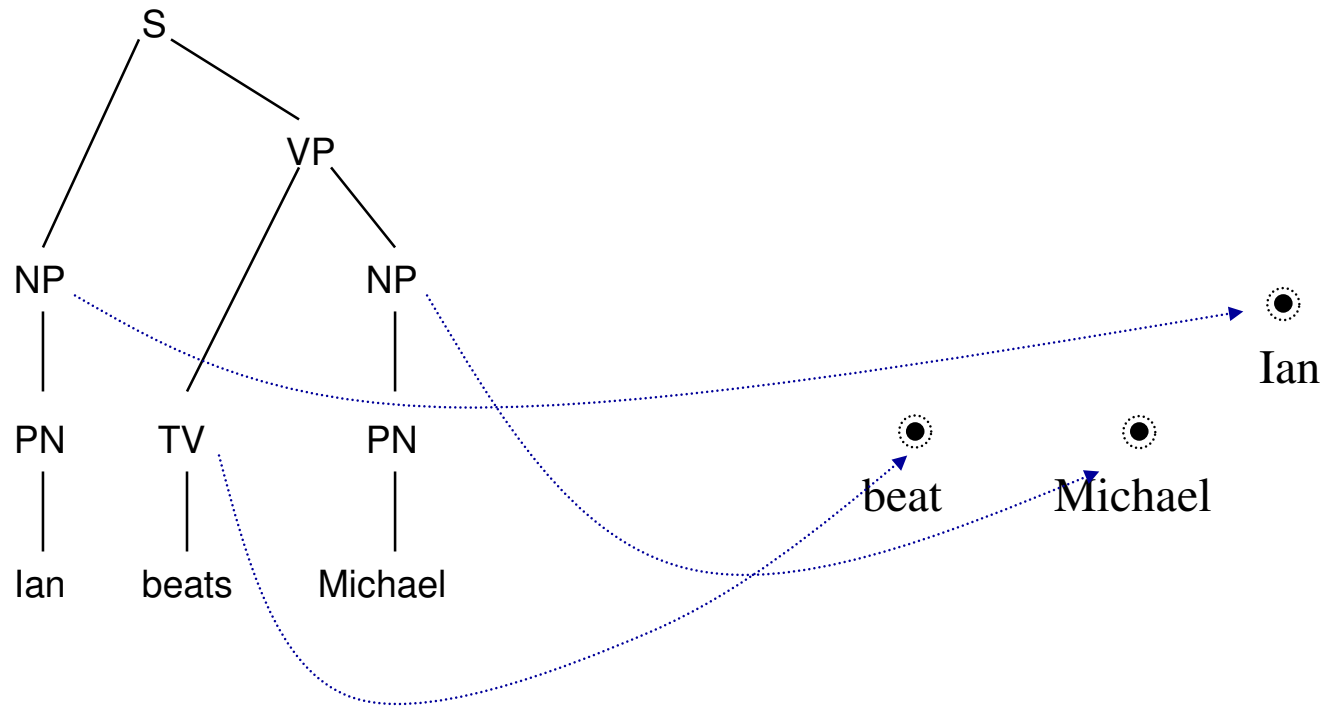
```
combine(vp:V, [tv:TV, np:NP]) :-  
  TV = usr([TVRoot|_],_,_,_),  
  NP = usr([NPRoot|_],_,_,_),  
  NewUsr = usr([Root], [Root:(TVRoot@NPRoot)],  
              [], []),  
  mergeUSR([NewUsr, TV, NP], V).
```



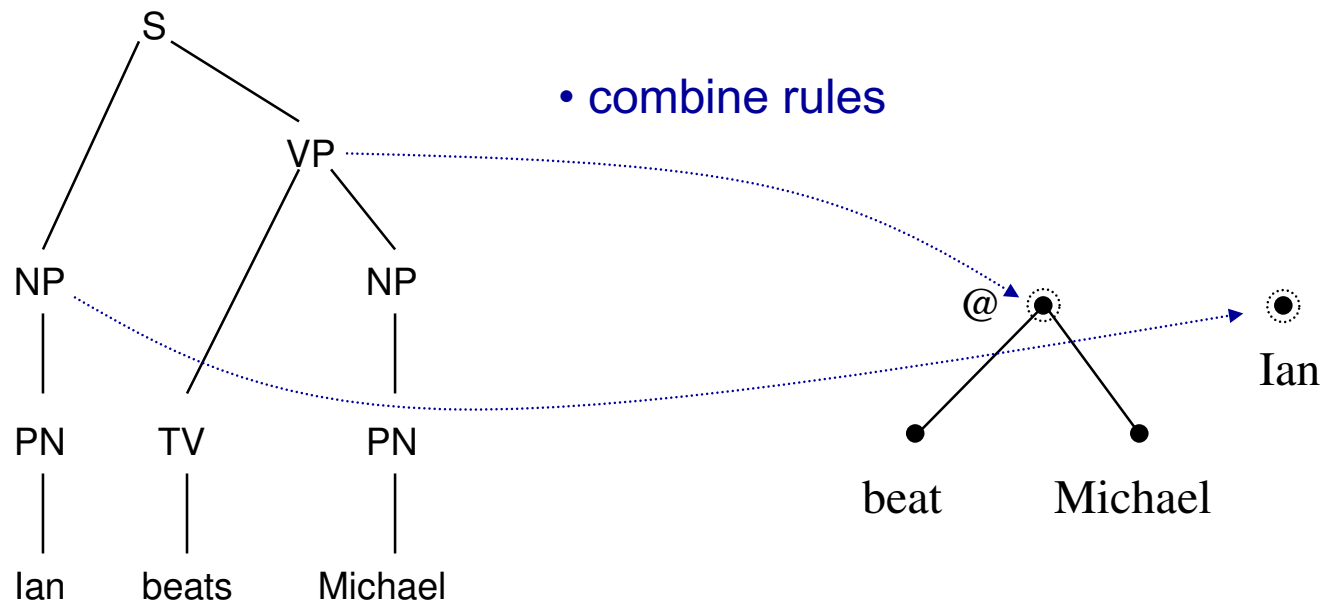
```
combine(s:S, [np:NP, vp:VP]) :-  
  NP = usr([TVRoot|_],_,_,_),  
  VP = usr([NPRoot|_],_,_,_),  
  NewUsr = usr([Root], [Root:(VPRoot@NPRoot)],  
              [], []),  
  mergeUSR([NewUsr, NP, VP], S).
```



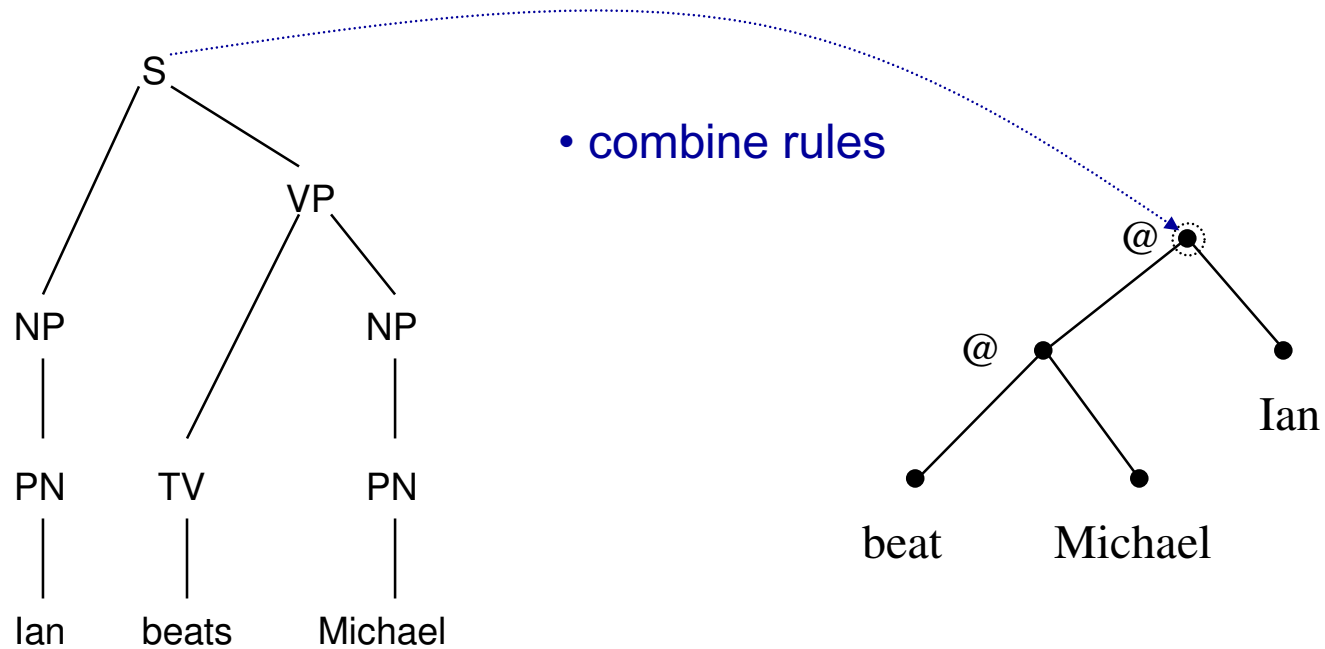
Semantics construction: The simple example



Semantics construction: The simple example

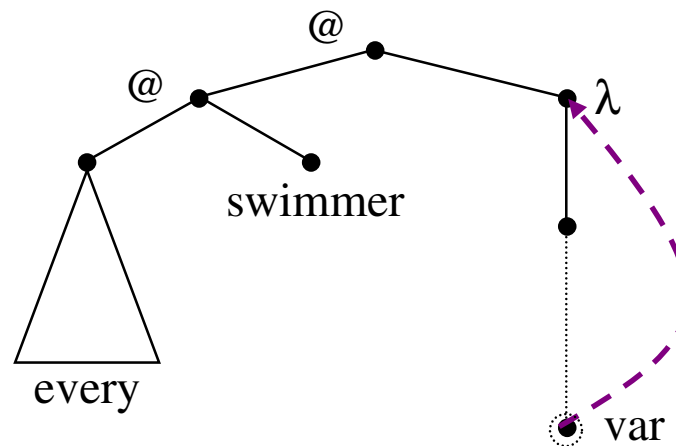


Semantics construction: The simple example



Quantifiers

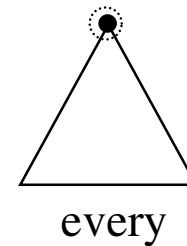
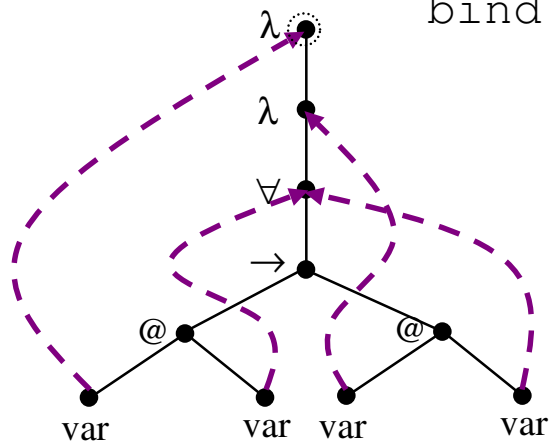
- ◆ The graph for a quantifier NP contains a variable node and its binder, linked by dominance and binding edges.
- ◆ The interface node of the graph is the variable node!



Semantic macro for determiners

```

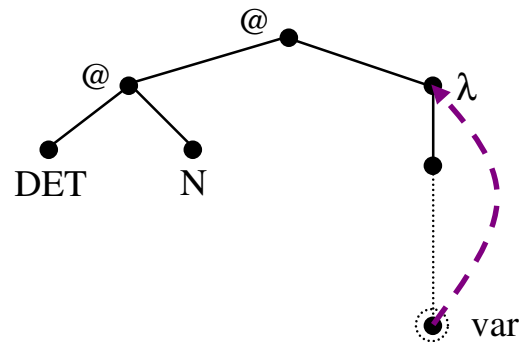
detSem (uni,
        usr ([Root, N1, N2, N3, N4, N5, N6, N7, N8, N9],
            [Root:lambda (N1), N1:lambda (N2),
             N2:forall (N3), N3:(N4 > N5),
             N4:(N6@N7), N5:(N8@N9), N6:var,
             N7:var, N8:var, N9:var],
            [],
            [bind (N6, Root), bind (N7, N2),
             bind (N8, N1), bind (N9, N2)])) .
    
```



$\lambda P \lambda Q \forall x.(P@x \rightarrow Q@x)$

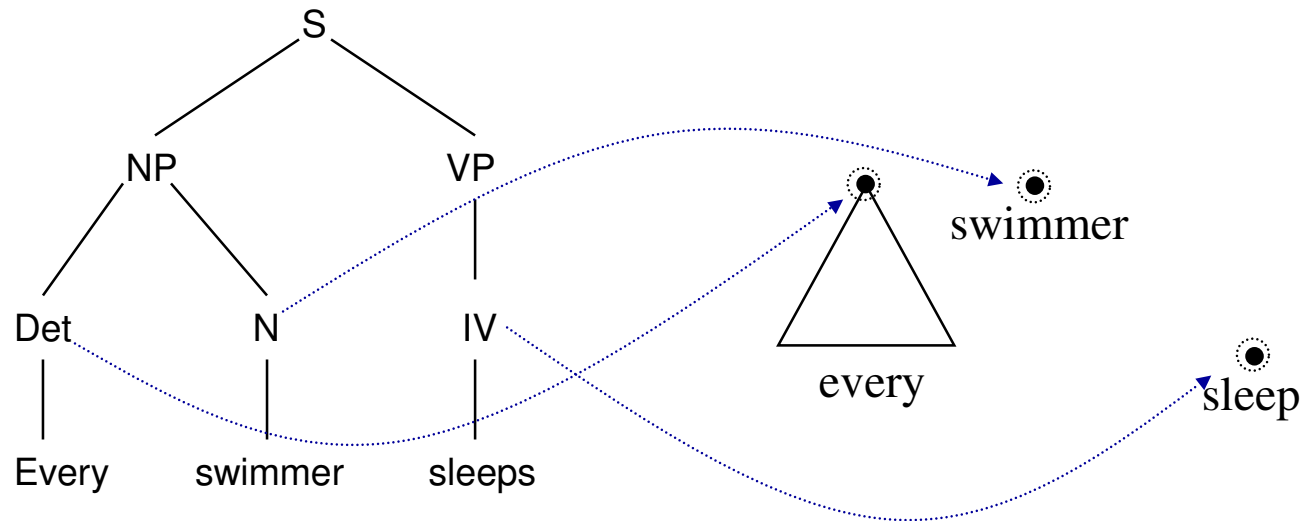
Combine rule for determiners

```
combine(np:NP, [det:DET, n:N]) :-  
  DET = usr([DETRoot|_], _, _, _),  
  N = usr([NRoot|_], _, _, _),  
  NewUsr = usr(. . . . .),  
  mergeUSR([NewUsr, TV, NP], V).
```

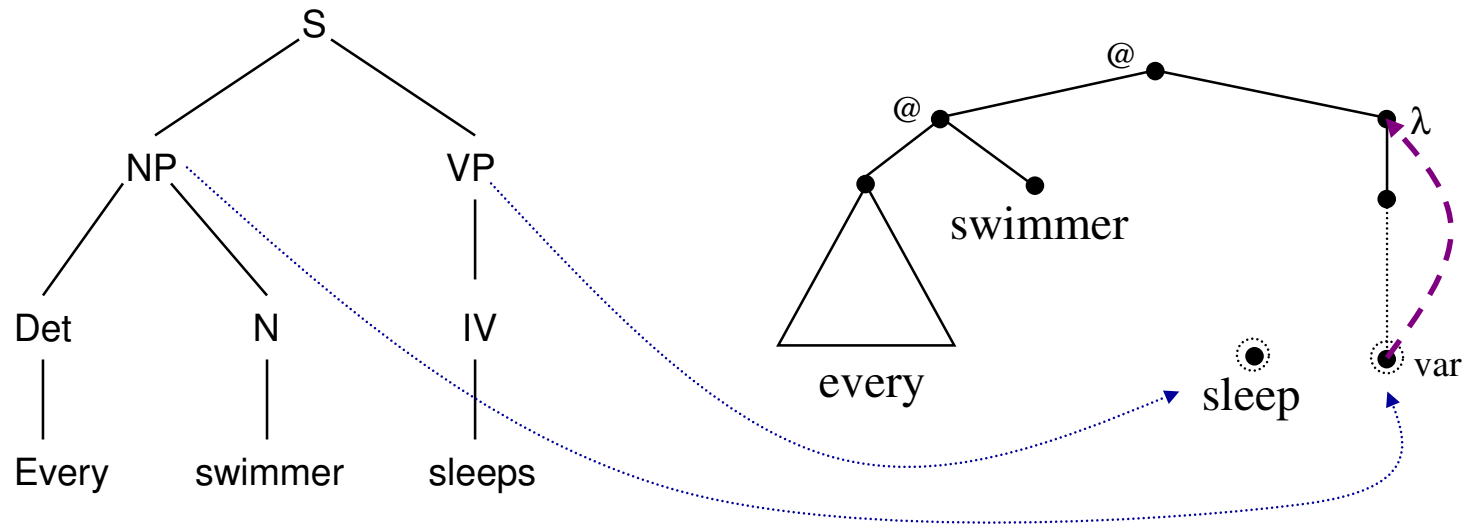


- ◆ This rule encodes Montague's Trick!

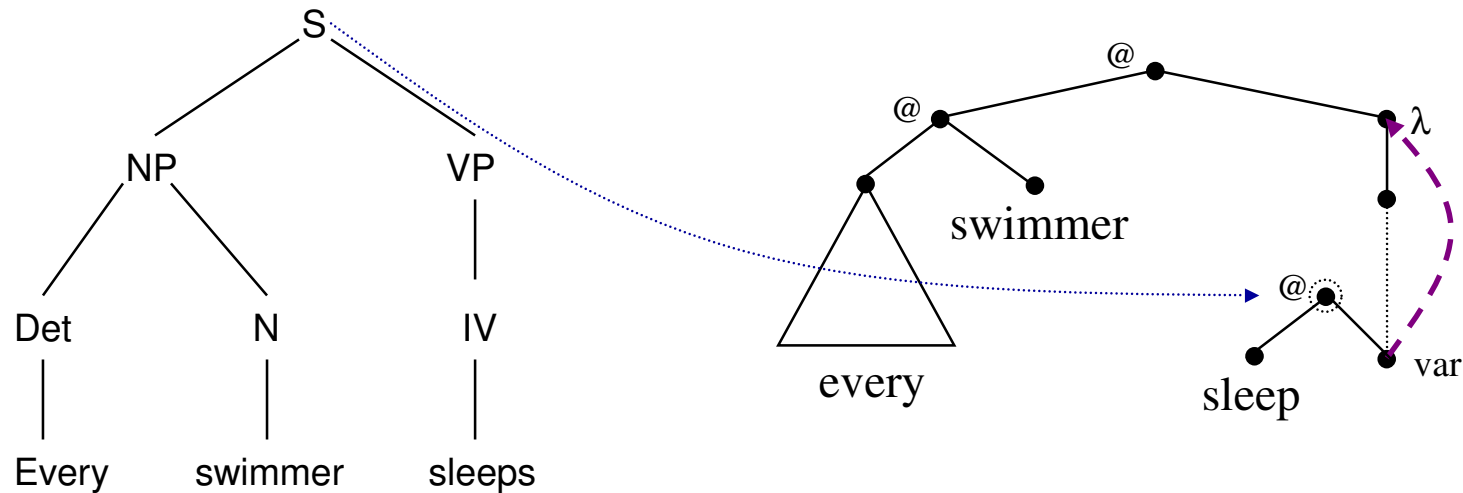
An example with determiners



An example with determiners

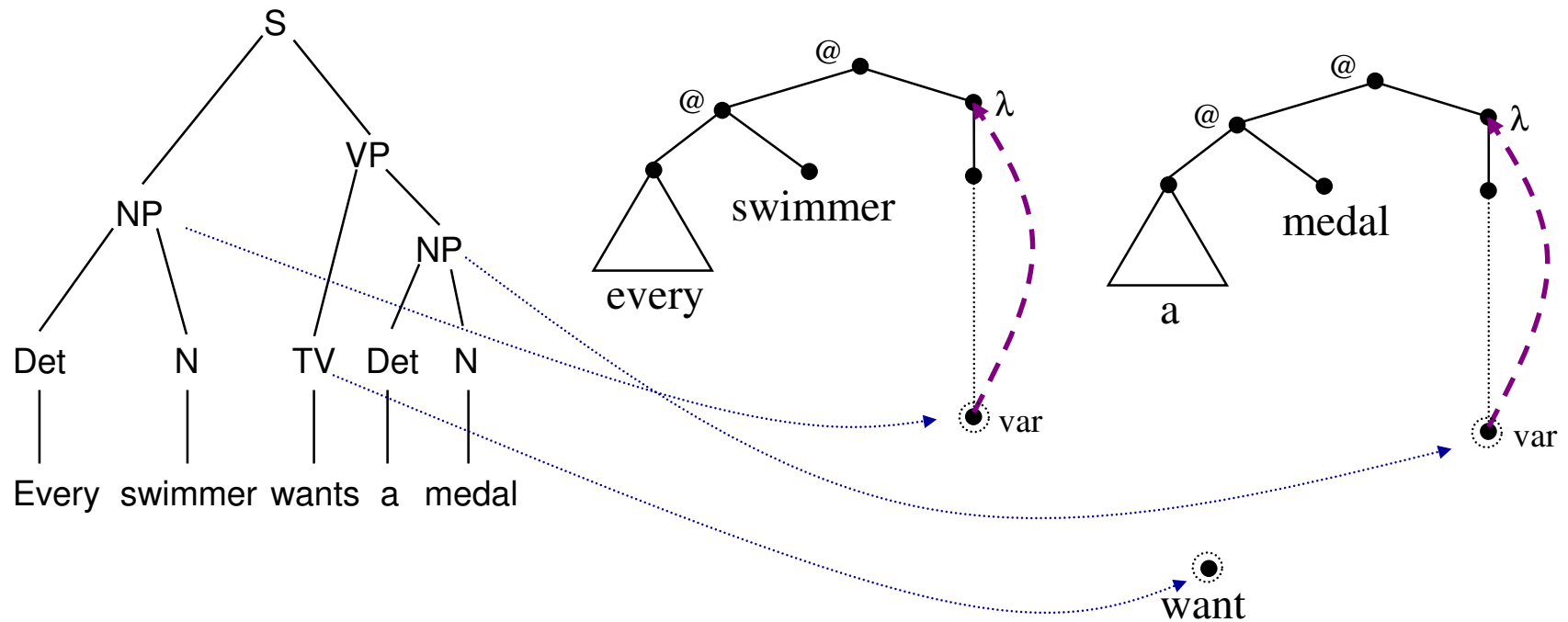


An example with determiners

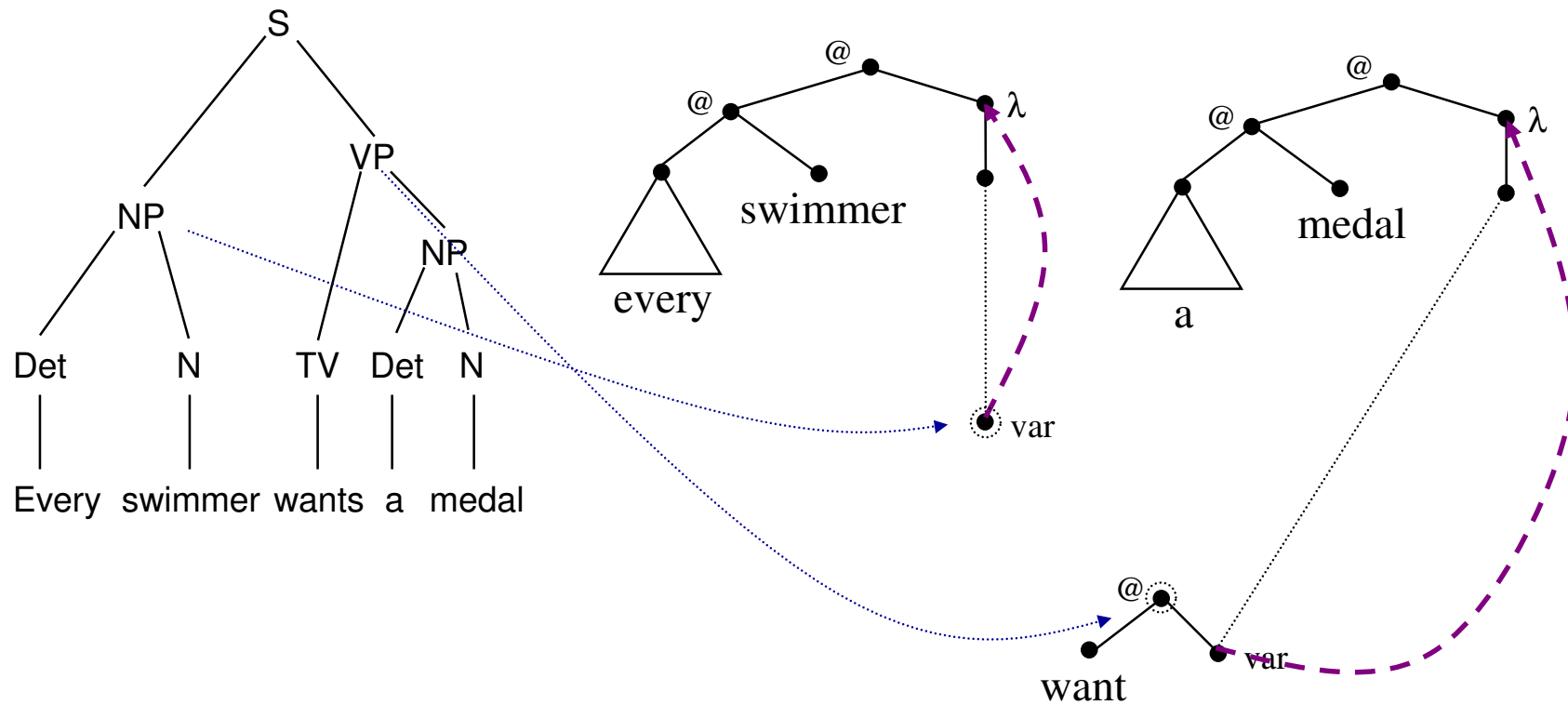


$\lambda P \lambda Q \forall x.(P@x \rightarrow Q@x)$
 $@ \text{ swimmer}$
 $@ (\lambda y.\text{sleep}@y)$

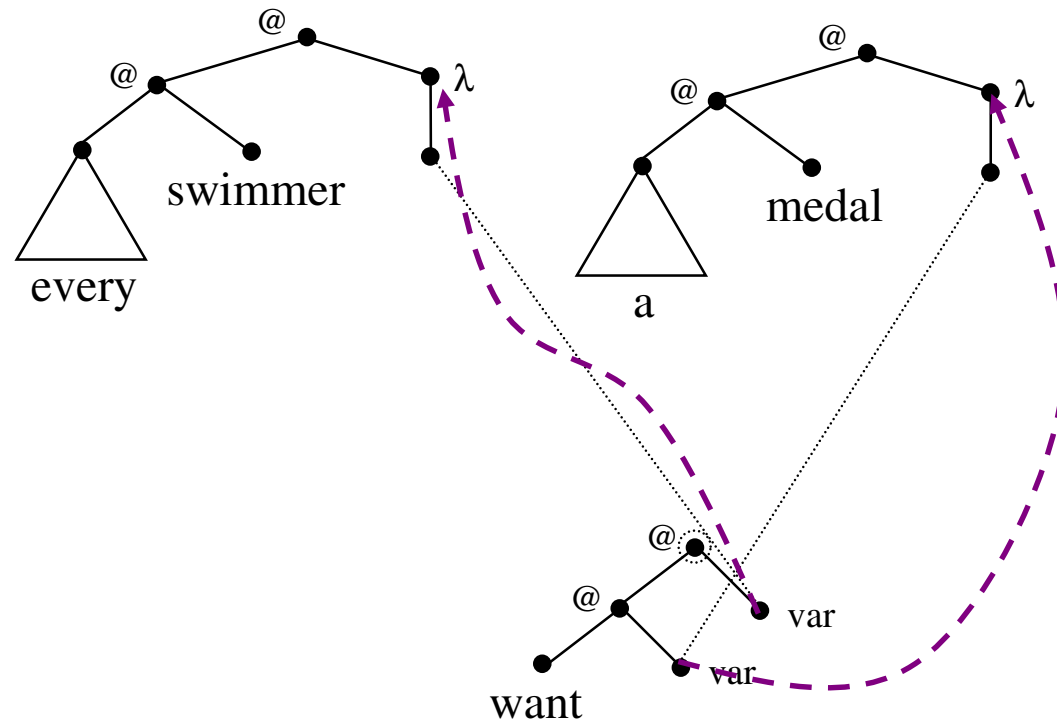
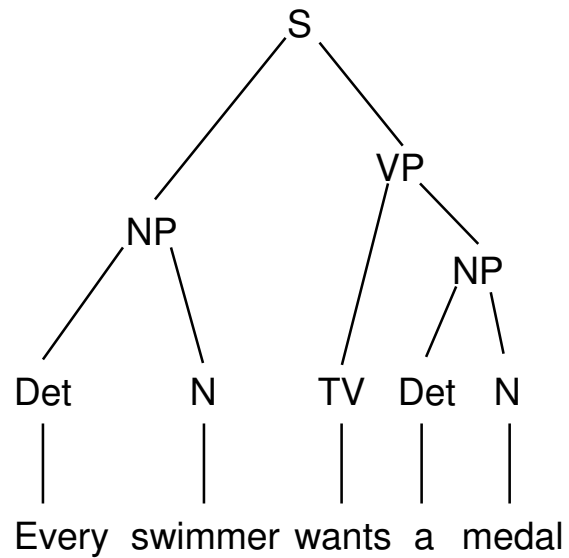
Scope ambiguities



Scope ambiguities



Scope ambiguities



Semantics construction: Summary

- ◆ By plugging new rules into yesterday's syntax-semantics framework, we can compute dominance graphs for English sentences.
- ◆ Changed semantic macros to give us dominance graphs for lexicon entries.
- ◆ Combine rules plug subgraphs together by connecting their interface nodes.
- ◆ Always apply verb semantics to interface variable of an argument NP.

Underspecification in semantics construction

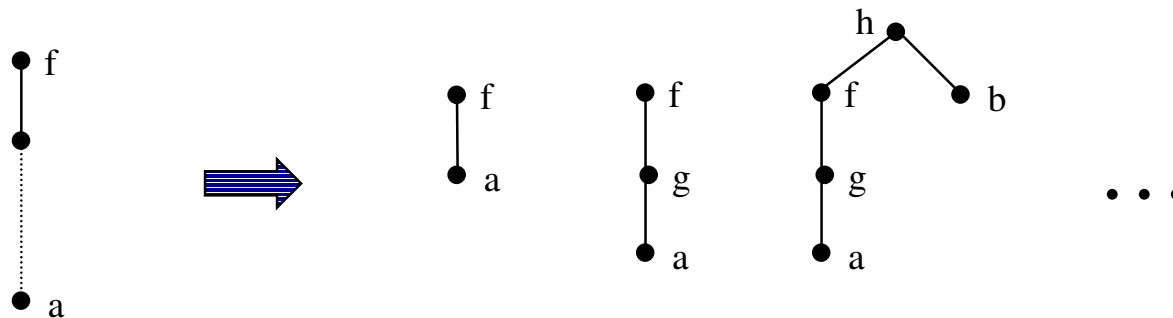
- ◆ Combine rule of determiners encodes Montague's Trick.
- ◆ Variable and binder are introduced together: No capturing necessary!
- ◆ Need fewer lambdas because we can now talk about positions in formulas explicitly.
- ◆ All large-scale grammars with semantics use some form of underspecification.

Solving Dominance Graphs

- ◆ Now we know
 - how to model scope ambiguities with dominance graphs
 - how to represent dominance graphs in Prolog
 - how to compute dominance graphs for English sentences.
- ◆ What's still missing: How to compute the trees (= formulas) that a graph represents?

Solved Forms

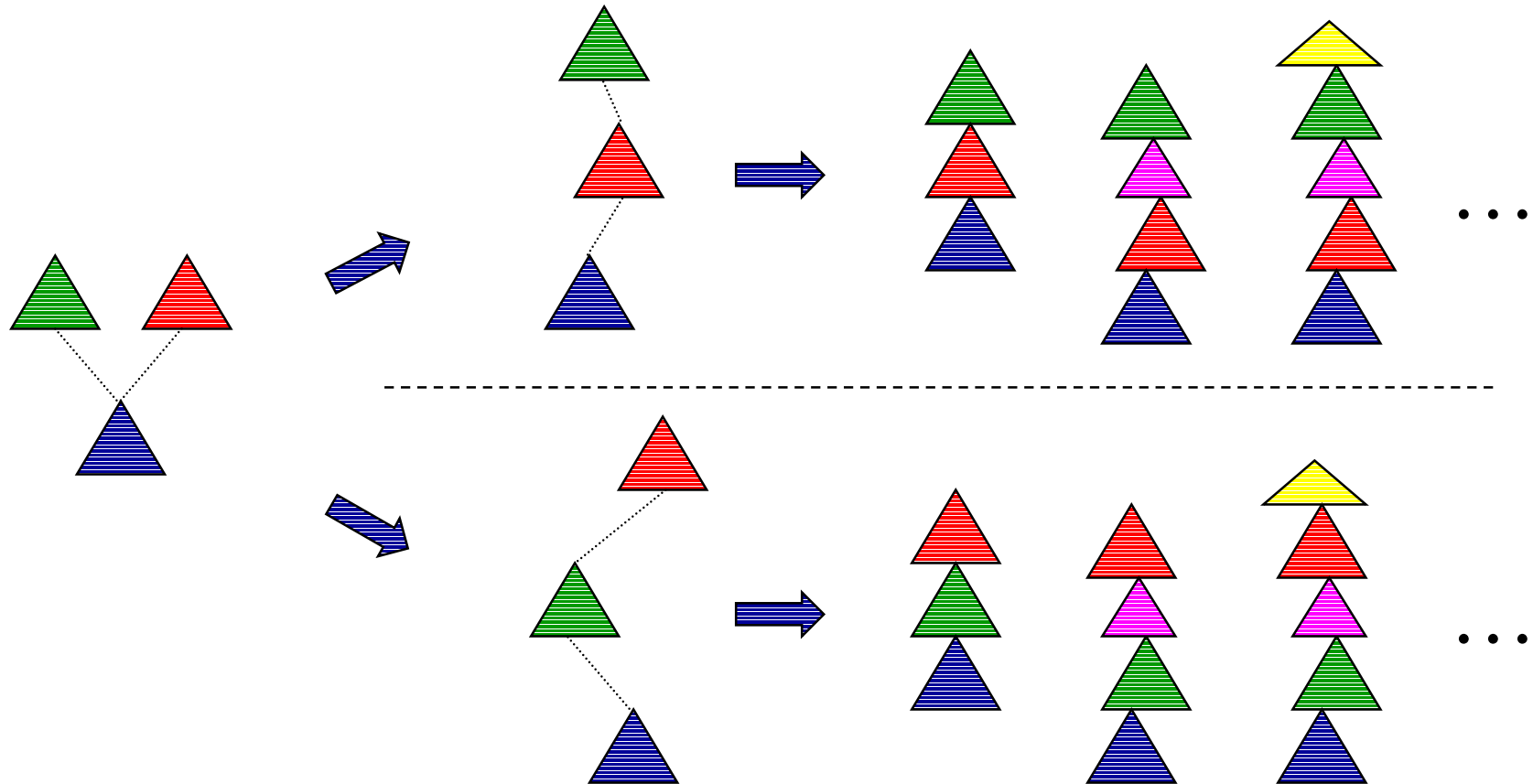
- ◆ We have seen yesterday that every solvable graph has an infinite number of solutions (= trees into which it can be embedded).



Solved Forms

- ◆ Thus, we aim at enumerating all **solved forms** of a dominance graph and not all solutions.
- ◆ A dominance graph in solved form is a graph whose tree and dominance edges are a forest.
- ◆ A graph G' is a **solved form of G** iff G' is in solved form and if there is a path from u to v in G (over tree and dominance edges), there is also a path from u to v in G' .

Solved Forms and Solutions



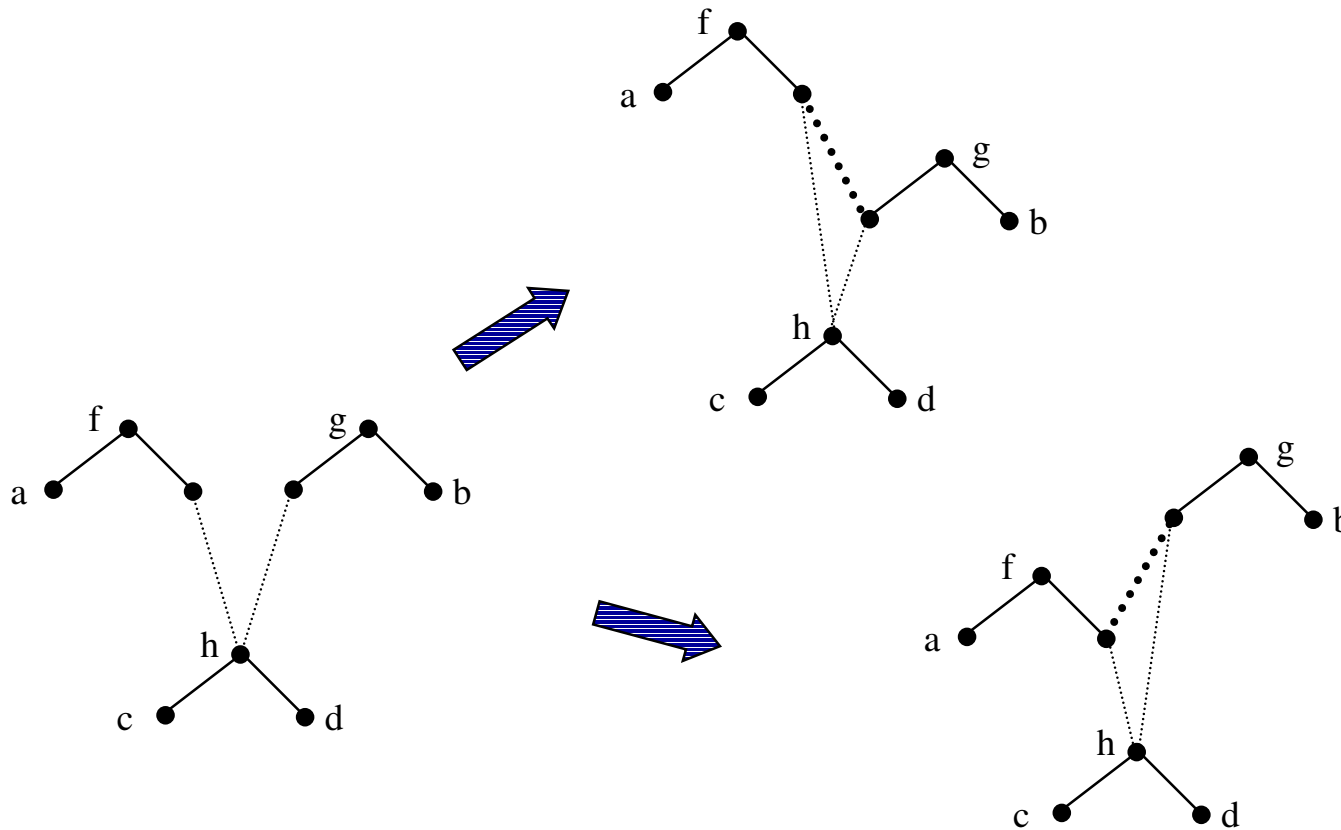
- ◆ Can consider solved forms as representatives of classes of solutions that only differ in "irrelevant details".

Solving Dominance Graphs

- ◆ Solver algorithm applies three graph simplification rules and then calls itself recursively:
 - Choice
 - Parent Normalisation
 - Redundancy Elimination
- ◆ Detect unsolvability: Test for cycles.
- ◆ Prolog implementation.

The Choice Rule

- ◆ Driving force behind solver is the Choice rule: Which of two trees comes first?

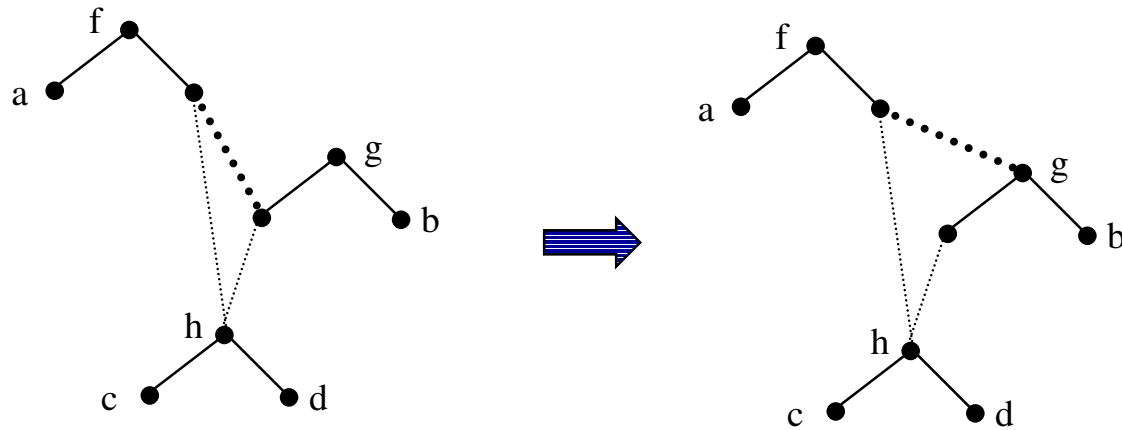


The Choice Rule

- ◆ Every application of Choice arranges the dominance parents of one node.
- ◆ Eventually, the dominance parents of all nodes will be arranged.
- ◆ Choice rule is sound: Every tree that satisfies original graph also satisfies one of the two possible results of the Choice application.

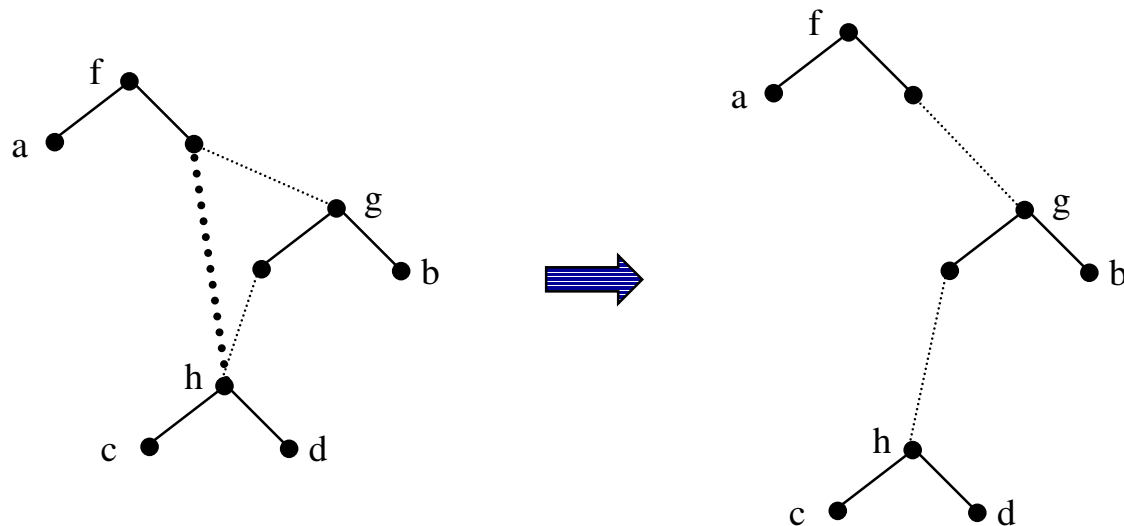
Cleaning Up I: Parent Normalisation

- ◆ Parent Normalisation changes a dominance edge (u,v) into a dominance edge (u,w) , where w is the parent of v over a solid edge.



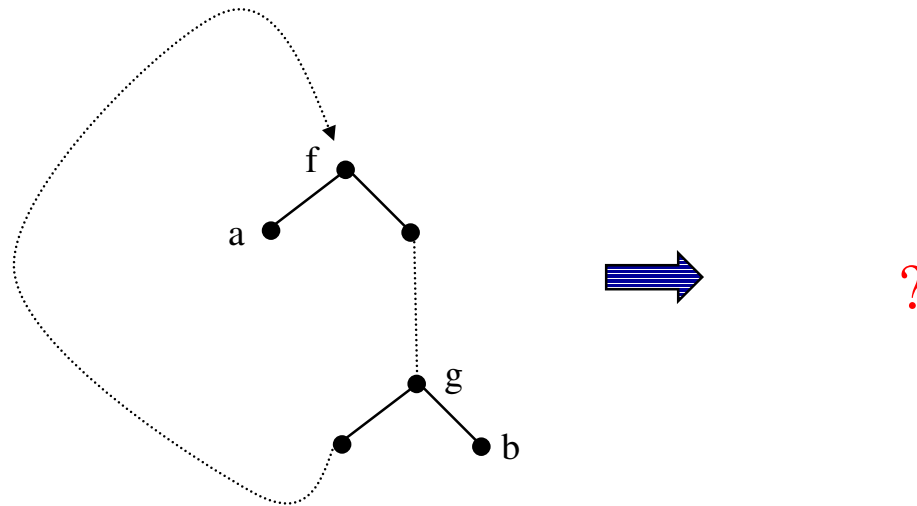
Cleaning Up II: Redundancy Elimination

- ◆ Redundancy Elimination deletes an edge (u,v) whenever there is a path from u to v that doesn't use this edge.



Detecting Unsolvability

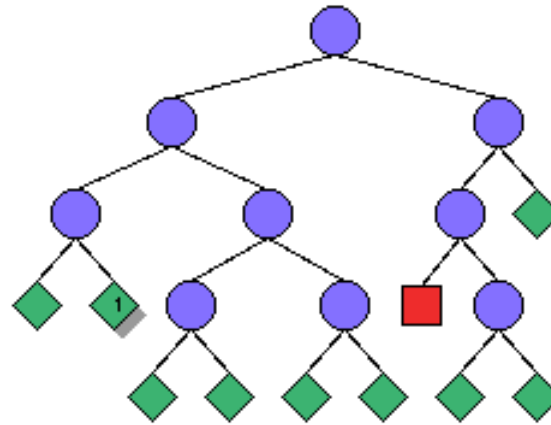
- ◆ Every dominance graph that has a cycle (using only tree and dominance edges) is unsolvable.



The Enumeration Algorithm

1. Apply Redundancy Elimination and Parent Normalisation exhaustively.
2. If the graph has a cycle, it is unsolvable.
3. If there is a node with two incoming dominance edges, pick one and apply Choice once. Then continue with Step 1 for each of the resulting graphs.
4. Otherwise, the dominance graph is in solved form.

Search Tree



The Algorithm in Prolog

Input:
An USR

Output:
List of solved forms

```
solve(Usr, SFs) :-  
    normalize(Usr, NormalUsr),  
    distribute(NormalUsr, Dist1, Dist2),  
    solve(Dist1, SFs1),  
    solve(Dist2, SFs2),  
    append(SFs1, SFs2, SFs).
```

Case 1:
Choice applicable

```
solve(Usr, [NormalUsr]) :-  
    normalize(Usr, NormalUsr),  
    \+ hasCycle(NormalUsr).
```

Case 2:
Solved Form

```
solve(_Usr, []).
```

Case 3:
Cycle

Subroutines

- ◆ The algorithm uses some other predicates. These are all available on the course website.
- ◆ Here we look at
 - distribute
 - elimRedundancy

The predicate "distribute"

```
distribute(usr(Ns, LCs, DCs, BCs),  
          usr(Ns, LCs, [dom(X, Y) | DCs], BCs),  
          usr(Ns, LCs, [dom(Y, X) | DCs], BCs)) :-  
  
  member(dom(X, Z), DCs),  
  member(dom(Y, Z), DCs),  
  X \== Y.
```

The predicate "elimRedundancy"

```
normalize(Usr, Normal) :-  
    parentNormalization(Usr, Lifted),  
    elimRedundancy(Lifted, Normal).
```

```
elimRedundancy(usr(Ns, LCs, DCs, BCs), Irr) :-  
    select(dom(X, Y), DCs, DCsRest),  
    reachable(Y, X, usr(Ns, LCs, DCsRest, BCs)),  
    !,  
    elimRedundancy(usr(Ns, LCs, DCsRest, BCs), Irr).
```

```
elimRedundancy(Usr, Usr).
```

A Note on Efficiency

- ◆ The implementation is correct, but:
 - checking for cycles is not a complete unsatisfiability test: Search space may be too large.
 - Redundancy Elimination, Choice, etc. are not implemented efficiently.
- ◆ Both problems can be solved. Best current implementations enumerate over 100.000 solved forms per second (Bodirsky et al. 2004).

A Note on Formalisms

- ◆ Dominance graphs are equivalent to normal dominance constraints (Althaus et al. 03; Egg et al. 01).
- ◆ Hole Semantics (Bos 96) can be encoded into normal dominance constraints (Koller et al. 03).
- ◆ MRS (Copestake et al. 99) can be encoded into normal dominance constraints (Niehren & Thater 03; Fuchss et al. 04).

Summary

- ◆ Semantics construction for dominance graphs:
 - use Tuesday's framework
 - use interface nodes to combine subgraphs
 - clean construction that introduces variables and binders together.
- ◆ Solving dominance graphs:
 - enumerate solved forms
 - driving force is Choice rule
 - Prolog implementation very concise
 - can be made efficient (not in Prolog)

State of the art in underspecification

- ◆ Well-understood formalisms.
- ◆ Efficient solvers are available.
- ◆ Large-scale grammars that compute underspecified semantic descriptions are available: e.g. English Resource Grammar (Copestake & Flickinger, 2000).
- ◆ Used, in one form or another, in most major grammars that define semantics.